

# Gilbert Chang

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## EDUCATION

### Purdue University

*Bachelor of Science in Mechanical Engineering, Computer Science*

West Lafayette, IN

Aug. 2023 – May 2027

**Concentrations:** Computational Science and Engineering

**Relevant Coursework:** Machine Design, Mechanics of Materials, Heat and Mass Transfer, Fluid Mechanics, Measurement and Control Systems II, Electrical Engineering Fundamentals II, Numerical Methods, Signals and Systems.

## EXPERIENCE

### Mechanical Engineering Intern

*Persona AI*

May 2025 – August 2025

Houston, TX

### Undergraduate Research Assistant

*Computational Motion, Manipulation, and Autonomy Lab at Purdue University*

November 2024 – Present

West Lafayette, IN

- Engineering polyurethane soft robotic gripper with optimized Finray geometries; designing custom molds to enhance manufacturability.
- Developing computational design pipelines integrating FEA/CFD simulations to optimize pressure channel placement for differential tactile sensing.

### Undergraduate Research Assistant

*Cai Group at Herrick Laboratories*

January 2025 – May 2025

West Lafayette, IN

- Implemented Python and MATLAB system identification pipelines for psychrometric chambers, utilizing convex optimization to fit experimental data to reduced-order models.
- Validated closed-loop system performance by replicating real-world dynamics using pipeline derived reduced-order transfer functions.

### Undergraduate Teaching Assistant

*Purdue University School of Electrical and Computer Engineering*

May 2024 – August 2024

West Lafayette, IN

- Evaluated and provided constructive feedback on weekly assignments for 200+ electrical engineering students.
- Conducted regular office hours, resolving technical inquiries and reinforcing course material.

### Undergraduate Research Assistant

*Purdue University School of Mechanical Engineering*

January 2024 – May 2024

West Lafayette, IN

- Optimized wheel hub design for forged carbon fiber manufacturability, reducing component weight by 40%.
- Streamlined bicycle frame weight with topology optimization, enforcing FoS requirements with FEA simulations.
- Investigated Kammtail virtual foils, 3D printed foil variants and test stands for wind tunnel validation.

## PROJECTS

### Canard Actuation Module

- Developed compact, high-degree-of-freedom linkage systems enabling servo control for rocket canard actuation.
- Conducted structural analysis using Ansys Mechanical, identifying and mitigating potential buckling under expected launch conditions.

### High Altitude Solid Rocket Motor

- Designed 44 kNs, 210 Isp SRM with parametric workflows in Onshape, achieving 98% ideal thrust coefficient.
- Performed FEA and manual stress analyses to ensure 3.5 Factor of Safety under anticipated operational loads.
- Applied DFM/DFA methodologies to optimize manufacturability of critical structural motor components.

## TECHNICAL SKILLS

**Design & Analysis:** Onshape, Siemens NX, SolidWorks, Autodesk Inventor, Ansys Mechanical, Ansys Fluent, KiCad

**Materials & Manufacturing:** Composites (VARTM, forged), GD&T, DFM/DFA, Tolerance Stack-ups

**Simulation & Control:** FEA, CFD, MATLAB, Simulink, ROS2, Python/C/C++/Java, NumPy, Pandas, Matplotlib

**Prototyping & Testing:** 3D Printing, Laser Cutting, Vacuum Forming, Manual & CNC Mills/Lathes, Bandsaws